CHM4M4 Simulation : Lecture Note

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(* = advanced topics)

1 Molecular Hamiltonian

Molecules = electrons + nuclei

$$H = T_N + T_e + V_{eN} + V_{ee} + V_{NN}$$

e.g., $T_N = -\sum_I \frac{\hbar^2}{2M_I} \nabla_I^2$, $V_{eN} = -\sum_I \sum_i \frac{Z_I}{|\mathbf{R}_I - \mathbf{r}_i|}$

Ideally, we wish to solve the whole problem,

$$H\Psi(\mathbf{R},\mathbf{r}) = E\Psi(\mathbf{R},\mathbf{r})$$

But this is too difficult for most of chemically interesting (complex) systems.

 \Rightarrow useful to separate the electronic and nuclear problems.

Electronc Hamiltonian

$$H_e = H - T_N = T_e + V_{eN} + V_{ee} + V_{NN}$$

2 Adiabatic Approximation (Born-Oppenheimer)

Stage 1 : Fix $\{\mathbf{R}\}$ and solve the electronic problem

$$H_e\varphi_n(\mathbf{r};\mathbf{R}) = W_n(\mathbf{R})\varphi_n(\mathbf{r};\mathbf{R})$$

 $\varphi_n(\mathbf{r}; \mathbf{R}) \cdots$ electronic wavefunction (parametrically dependent on $\{\mathbf{R}\}$)

 $W_n(\mathbf{R}) \cdots$ electronic energy levels at $\{\mathbf{R}\}$

Stage 2 : Repeat at various $\{\mathbf{R}\}$

 \Rightarrow Potential energy surface $W_n(\mathbf{R})$

Diagram : Potential energy curves W_1 and W_2 (diatomic)

• Stages 1-2 = "Quantum chemistry" (narrow meaning)

Stage 3: Examine nuclear dynamics on PES $W_n(\mathbf{R})$

• quantum energy levels :

 $H_n^{(N)} \equiv T_N + W_n(\mathbf{R})$ (nuclear Hamiltonian on *n*-th PES) $H_n^{(N)}\chi_v(\mathbf{R}) = E_{n,v}\chi_v(\mathbf{R})$

• quantum dynamics : wavepacket simulations, $i\hbar \frac{\partial}{\partial t} \chi_n(\mathbf{R}) = H_n^{(N)} \chi_v(\mathbf{R})$

- classical dynamics : moelcular dynamics (MD) simulations, $M_I \ddot{\mathbf{R}} = -\frac{\partial W_n(\mathbf{R})}{\partial \mathbf{R}}$
- statistical mechanics : Monte Carlo simulations (quantum or classical)

Stage 4: Analysis of simulation results (statistical or dynamical)

3 Non-adiabatic couplings*

Expand the total wavefunction in terms of the electronic wavefunction $\{\varphi_n(\mathbf{r}; \mathbf{R})\}$

$$\Psi(r,R) = \sum_{n} \chi_n(R)\varphi_n(r;R)$$
(1)

Schrödinger equation with the total Hamiltonian: $H = T_N + H_e$

$$[T_N + H_e]\Psi(r, R) = E\Psi(r, R)$$
⁽²⁾

Put (1) into (2), multiply φ_k^* and integrate over the electronic coordinate (i.e., $\langle \varphi_k | \times \rangle$) Use $H_e \varphi_n = W_n \varphi_n$ and $\langle \varphi_k | \varphi_n \rangle = \delta_{kn}$,

$$\sum_{n} \langle \varphi_k(r; R) | T_N | \varphi_n(r; R) \rangle \chi_n(R) + W_k(R) \chi_k(R) = E \chi_k(R)$$
(3)

Noting that $T_N = -\sum_I (\hbar^2/2M_I) \nabla_I^2$ operates to both $\varphi(r; R)$ and $\chi(R)$,

$$\sum_{n} \left[\langle \varphi_k | T_N | \varphi_n \rangle - \sum_{I} \frac{\hbar^2}{M_I} \langle \varphi_k | \nabla_I | \varphi_n \rangle \cdot \nabla_I \right] \chi_n(R)$$
(4)

 $+T_N\chi_k(R) + W_k(R)\chi_k(R) = E\chi_k(R)$

[Here, T_N and ∇_I within $\langle \varphi | \cdots | \varphi \rangle$ do not operate to the further right]

Adiabatic approximation: Neglect the 1st line of (4)

$$[T_N + W_k(R)]\chi_k(R) = E\chi_k(R) \quad (=i\hbar\frac{\partial\chi_k}{\partial t})$$
(5)

 \Leftarrow Schrödinger eq for the nuclear wfn $\chi(R)$ on a (single adiabatic) PES $W_k(R)$

neglected terms = Non-adiabatic couplings

 \Rightarrow induce mixing/transition among different electronic states $k \leftrightarrow n$

- 1st order NA coupling : $\frac{\hbar^2}{M_I} \langle \varphi_k | \nabla_I | \varphi_n \rangle$
- 2nd order NA coupling : $\frac{\hbar^2}{2M_I} \langle \varphi_k | \nabla_I^2 | \varphi_n \rangle$

3.1 Mixed Quantum-classical Simulation

Assume: Nuclear motions follow classical trajectories $\mathbf{R}(t)$

$$\Phi(\mathbf{r}, \mathbf{R}, t) \simeq \sum_{n} c_n(t) \varphi_n(\mathbf{r}; \mathbf{R}(t))$$
(6)

 $|c_n(t)|^2$ = probability of finding the system in the *n*-th electronic state.

How to determine $\mathbf{R}(t)$? — not a trivial task

- Most conveniently, classical trajectories on the adiabatic PES $W_n(R)$
- Then, switch among PES's via non-adiabatic transitions ("surface-hopping")

Diagram : Curve crossing

Put (6) into the time-dependent Schrödinger eq : $i\hbar \frac{\partial \Phi}{\partial t} = [T_N + H_e]\Phi$

$$i\hbar\sum_{n} \left(\frac{\partial c_n}{\partial t}\varphi_n + c_n \frac{\partial \varphi_n}{\partial t}\right) = \sum_{n} c_n [T_N + W_n(R)]\varphi_n$$

Multiply φ_k^* and integrate over the electronic coordinates (i.e., $\langle \varphi_k^* | \times \rangle$) Note the orthonormality $\langle \varphi_k | \varphi_n \rangle = \delta_{kn}$

$$i\hbar\frac{\partial c_k}{\partial t} + i\hbar\sum_n c_n \left\langle \varphi_k | \frac{\partial \varphi_n}{\partial t} \right\rangle = W_k(R)c_k + \sum_n c_n \left\langle \varphi_k | T_N | \varphi_n \right\rangle$$

• Neglect the 2nd order NA couplings $\langle \varphi_k | T_N | \varphi_n \rangle$

• Use
$$\left\langle \varphi_k | \frac{\partial}{\partial t} \varphi_n(\mathbf{r}; \mathbf{R}(t)) \right\rangle = \left\langle \varphi_k | \nabla_R | \varphi_n \right\rangle \cdot \dot{\mathbf{R}}(t) \equiv \mathbf{d}_{kn}(\mathbf{R}) \cdot \dot{\mathbf{R}}(t)$$

 $\Rightarrow i\hbar \dot{c}_k(t) = W_k(\mathbf{R})c_k(t) - i\hbar \sum_n \mathbf{d}_{kn}(\mathbf{R}) \cdot \dot{\mathbf{R}}(t)c_n(t)$

(coupled equations for the probability amplitudes $\{c_n(t)\}$)

4 Electronic part (Quantum chemistry)

4.1 Hartree-Fock Method

Electronic Hamiltonian

$$H_e = T_e + V_{eN} + V_{ee} + V_{NN}$$

$$= \sum_i \left(-\frac{\hbar^2}{2m} \nabla_i^2 - \sum_I \frac{Z_I}{R_{Ii}} \right) + \sum_{i < j} \frac{1}{r_{ij}} + \sum_{I < J} \frac{Z_I Z_J}{R_{IJ}}$$

$$= \sum_i H^{core}(i) + V_{ee} + V_{NN}$$

$$(7)$$

 V_{NN} is just a constant in the electronic problem (adiabatic approximation), so we hereafter consider $h_e \equiv H_e - V_{NN}$

Two-electron molecules (e.g., H_2)

$$h_e = H^{core}(1) + H^{core}(2) + \frac{1}{r_{12}}$$

Slater determinant : $\psi(1,2) = \frac{1}{\sqrt{2}} \begin{vmatrix} \varphi_1(1) & \varphi_1(2) \\ \varphi_2(1) & \varphi_2(2) \end{vmatrix} = \frac{1}{\sqrt{2}} (\varphi_1(1)\varphi_2(2) - \varphi_2(1)\varphi_1(2)) = \frac{1}{\sqrt{2}} |\varphi_1\varphi_2|$

Spin-orbitals :

$$\begin{aligned}
\varphi_1(1) &= \phi_1(1)\alpha(1) = \phi_1(1) \\
\varphi_2(1) &= \phi_1(1)\beta(1) = \overline{\phi}_1(1)
\end{aligned}$$
(space orbital) × (spin function α, β)

Diagram : orbital diagrams $\phi_1 \bar{\phi}_1, \, \phi_1 \bar{\phi}_2, \, \phi_1 \phi_2$

Slater-determinants satisfy the **Pauli-Principle** of many-electron systems:

- Anti-symmetry : $\psi(2,1) = -\psi(1,2)$
- Exclusion principle : $\psi(1,2) = 0$ if $\varphi_1 = \varphi_2$ (space and spin)

Energy: $E = \langle \psi(1,2) | h_e | \psi(1,2) \rangle = \int \int \psi(1,2)^* h_e \psi(1,2) d\tau_1 d\tau_2$

$$=\frac{1}{2}(\langle\phi_1(1)\bar{\phi}_1(2)|h_e|\phi_1(1)\bar{\phi}_1(2)\rangle - \langle\phi_1\bar{\phi}_1|h_e|\bar{\phi}_1\phi_1\rangle - \langle\bar{\phi}_1\phi_1|h_e|\phi_1\bar{\phi}_1\rangle + \langle\bar{\phi}_1\phi_1|h_e|\bar{\phi}_1\phi_1\rangle)$$

- The 1st term = $\langle \phi_1(1)\bar{\phi}_1(2)|H^{core}(1) + H^{core}(2) + \frac{1}{r_{12}}|\phi_1(1)\bar{\phi}_1(2)\rangle$ = $\langle \phi_1(1)|H^{core}(1)|\phi_1(1)\rangle\langle\bar{\phi}_1(2)|\bar{\phi}_1(2)\rangle + \langle \phi_1(1)|\phi_1(1)\rangle\langle\bar{\phi}_1(2)|H^{core}(2)|\bar{\phi}_1(2)\rangle + \langle \phi_1\bar{\phi}_1|\frac{1}{r_{12}}|\phi_1\bar{\phi}_1\rangle$ $\equiv 2H_{11}^{core} + J_{11}$
- The 4th term gives the same result : $2H_{11}^{core} + J_{11}$

• The 2nd term =
$$\langle \phi_1 | H^{core} | \bar{\phi}_1 \rangle \langle \bar{\phi}_1 | \phi_1 \rangle + \langle \phi_1 | \bar{\phi}_1 \rangle \langle \bar{\phi}_1 | H^{core} | \phi_1 \rangle + \langle \phi_1 \bar{\phi}_1 | \frac{1}{r_{12}} | \bar{\phi}_1 \phi_1 \rangle$$

= 0 because $\langle \alpha | \beta \rangle = 0$

• The 3rd term is also zero.

Thus, $E = 2H_{11}^{core} + J_{11}$

Let us next consider an open-shell singlet configuration $|\phi_1 \bar{\phi}_2|$ (α electron in ϕ_1 and β in ϕ_2) In the similar way, we get

$$E = H_{11}^{core} + H_{22}^{core} + J_{12}$$

where $J_{12} \equiv \langle \phi_1 \phi_2 | \frac{1}{r_{12}} | \phi_1 \phi_2 \rangle \equiv \langle 12 | | 12 \rangle = J_{21} = \langle \phi_2 \phi_1 | \frac{1}{r_{12}} | \phi_2 \phi_1 \rangle \equiv \langle 21 | | 21 \rangle$ Triplet configuration $| \phi_1 \phi_2 |$ (α electrons in both ϕ_1 and ϕ_2) gives

$$E = H_{11}^{core} + H_{22}^{core} + J_{12} - K_{12}$$

where $K_{12} \equiv \langle 12 | | 21 \rangle = K_{21}$

J_{ij} and K_{ij} are called **Coulomb** and **Exchange** integrals, respectively.

These examples suggest the following rule to write down **energies** of **electron configurations**

• Each electron in orbital ϕ_i contributes H_{ii}^{core}

- Each electron pair in orbitals ϕ_i and ϕ_j contributes J_{ij} (regardless of the spin)
- Each electron pair of the same spin in orbitals ϕ_i and ϕ_j contributes $-K_{ij}$

Exercise : Write down the energy expression for the following electron configurations.

- 1. α and β electron pair in ϕ_1 and an α electron in ϕ_2 (open-shell doublet)
- 2. paired (α and β) electrons in both ϕ_1 and ϕ_2 (closed-shell)

Answer :

1.
$$E = 2H_{11}^{core} + H_{22}^{core} + J_{11} + 2J_{12} - K_{12}$$

2. $E = 2H_{11}^{core} + 2H_{22}^{core} + J_{11} + J_{22} + 4J_{12} - 2K_{12}$

In general, for closed-shell N-electron systems,

$$E = \sum_{i=1}^{N/2} H_{ii}^{core} + \sum_{i=1}^{N/2} J_{ii} + \sum_{i=1}^{N/2} \sum_{j=i+1}^{N/2} (4J_{ij} - 2K_{ij})$$

This can be simplified by noting $J_{ii} = K_{ii}$

$$E = \sum_{i=1}^{N/2} H_{ii}^{core} + \sum_{i=1}^{N/2} \sum_{j=1}^{N/2} (2J_{ij} - K_{ij})$$

Hartree-Fock Method

= find <u>variationally best</u> MOs $\{\phi_i\}$ under the orthonormality condition $\langle \phi_i | \phi_j \rangle = \delta_{ij}$ \Rightarrow minimize $L \equiv E + \sum_i \sum_j \epsilon_{ij} (\delta_{ij} - \langle \phi_i | \phi_j \rangle)$ w.r.t. the variation of MOs $\phi_i \rightarrow \phi_i + \delta \phi_i$ (where ϵ_{ij} is the Lagrange multiplier)

 $\Rightarrow \text{Hartree-Fock equation}: \hat{F}_i \phi_i = \sum_j \epsilon_{ij} \phi_j$ where the Fock-operator is defined as $\hat{F}_i \equiv \hat{H}^{core} + \sum_{j=1}^{N/2} (2\hat{J}_j - \hat{K}_j)$ [for closed-shell systems] The Coulomb and Exchange operators \hat{J}_j and \hat{K}_j are defined by

$$\hat{J}_{j}(1)\phi_{i}(1) = \langle \phi_{j}(2)|\frac{1}{r_{12}}|\phi_{j}(2)\rangle\phi_{i}(1)$$
$$\hat{K}_{j}(1)\phi_{i}(1) = \langle \phi_{j}(2)|\frac{1}{r_{12}}|\phi_{i}(2)\rangle\phi_{j}(1)$$

Comment: The bottleneck for the first-learner would be the abstractness of the functional variation of MOs $\phi_i \rightarrow \phi_i + \delta \phi_i$. In practical calculations, however, we employ LCAO-MO expansion of the MOs $\phi_i = \sum_{\nu} c_{\nu i} \chi_{\nu}$ where χ is the atomic orbitals (AO), and optimize

the coefficients $c_{\nu i}$. This reduces the problem to a (non-linear) matrix eigenvalue problem which is much more handy for computer implementations. (Hartree-Fock-Roothaan-Hall method)

Summary of Hartree-Fock method

- Assumes a single Slater-determinant for the electronic wavefunction, which satisfies the Pauli Principle of many-electron systems
- and variationally optimizes the MOs by minimizing the exact energy expression for the Slater-determinant wavefunction under the orthonormality condition of the MOs.
- The electronic energy is expressed by one-electron integrals H_{ii}^{core} and Coulomb and Exchange two-electron integrals J_{ij} and K_{ij} .

4.2 Electron Correlation Problem

4.2.1 Static and Dynamic Correlations

4.2.2 Various Methods

• CI, MPn, MCSCF, MRCI, CC, MRMP, etc.

4.3 Density Functional Theory

- 4.3.1 Kohn-Sham theory
- 4.3.2 Hybrid Hartree-Fock / DFT

4.4 Other Methods

- Valence-Bond Method
 - non-orthogonal orbitals
 - chemically intuitive resonance structures
- Semi-empirical MO Methods
 - Approximations: neglect of differential overlaps, empirical parameters
 - CNDO, INDO, MINDO, PM3, AM1, etc. etc.

5 Potential Energy Surfaces

Functional fitting

- Choice of the functional form (physically adequate asymptotic behavior, symmetry etc.)
- Empirical parametrization using e.g. spectroscopic data
- Ab initio parametrization using quantum chemical calculations
- Dimensionality problem : when the system has f degrees of freedom (f = 3N 6 for non-linear N-atoms molecules), and if M data points are needed per degree of freedom for the functional fitting, the total number of data points required, M^f , may be prohibitively huge for realistic systems. (e.g., $M \sim 10$ and N = 6 requires 10^{12} points.)

On-the-fly evaluation of the potential $W_n(R)$ and gradient $\partial W_n/\partial R$

- Ab initio MD, Car-Parrinello MD
- Still computationally expensive, but becoming feasible along with the increase of the computer power

5.1 Empirical Force-Field

Standard FF for MD simulations of biomolecules

$$W = \sum_{bonds} K_R (R - R_e)^2 + \sum_{angles} K_\theta (\theta - \theta_e)^2 + \sum_{torsions} V_n [1 + \cos(n\phi - \gamma)]$$
$$+ \sum_{atoms(i < j)} \frac{Q_i Q_j}{r_{ij}} + \sum_{atoms(i < j)} 4\epsilon_{ij} \left[\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - \left(\frac{\sigma_{ij}}{r_{ij}} \right)^6 \right]$$

- First three terms = bonding potential
- Last two terms = non-bonding interaction (Electrostatic + Short-range repulsion)
- Inadequate for bond-breaking and -forming processes
- Lack of electronic polarization effects, charge-transfer interaction

5.2 Hybrid Methods*

5.2.0 Classical Mechanics

$$M_I \ddot{R}_I(t) = -\frac{\partial}{\partial R_I} W_e^{\text{model}}(R(t))$$

5.2.1 TDSCF MD

- On-the-fly evaluation of the local potential $W(R) = \langle \Psi_0(r;R) | H_e(r;R) | \Psi_0(r;R) \rangle_e$
- Time-dependent propagation of the (ground state) electronic wavefunction $\Psi_0(r; R)$.

$$\begin{cases} M_I \ddot{R}_I(t) &= -\frac{\partial}{\partial R_I} \langle \Psi_0 | H_e | \Psi_0 \rangle \\ \\ i\hbar \frac{\partial \Psi_0}{\partial t} &= H_e \Psi_0 \end{cases}$$

Simple model of Ψ_0 is often employed (rather than carrying out quant. chem. calculations), e.g., basis function expansion $\Psi_0(t) = \sum_i c_i(t)F(r; R)$

5.2.2 Born-Oppenheimer MD

$$\begin{cases} M_I \ddot{R}_I(t) = -\frac{\partial}{\partial R_I} \min_{\Psi_0} \{ \langle \Psi_0 | H_e | \Psi_0 \rangle \} \\ E_0 \Psi_0 = H_e \Psi_0 \end{cases}$$

Optimize the electronic wavefunction Ψ_0 at each nuclear configuration R (rather than propagating it as in TDSCF MD).

5.2.3 Hartree-Fock BO MD

If we employ the Hartree-Fock wavefunction : $\Psi_0^{\text{HF}} = \det\{\psi_i\}$ where $\psi_i = \text{HF}$ orbitals (1-electron, orthonormal),

$$\min_{\Psi_0} \{ \langle \Psi_0 | H_e | \Psi_0 \rangle \} \Rightarrow \min_{\{\psi_i\}} \{ \langle \Psi_0^{\rm HF} | H_e | \Psi_0^{\rm HF} \rangle \} \bigg|_{\langle \psi_i | \psi_j \rangle = \delta_{ij}}$$

i.e., minimization within the $\{\psi_i\}$ -space under the constraint $\langle \psi_i | \psi_j \rangle = \delta_{ij}$.

HF Lagrangian :
$$\mathcal{L}_{e}^{\mathrm{HF}} = \langle \Psi_{0}^{\mathrm{HF}} | H_{e} | \Psi_{0}^{\mathrm{HF}} \rangle - \sum_{i,j} \epsilon_{ij} (\langle \psi_{i} | \psi_{j} \rangle - \delta_{ij})$$

 $\epsilon_{ij} = \text{Lagrange multipliers}$

Variational (stationary) condition :

$$\frac{\delta \mathcal{L}_e^{\rm HF}}{\delta \psi_i^*} = \frac{\delta \mathcal{L}_e^{\rm HF}}{\delta \psi_i} = 0 \quad \Rightarrow \quad \hat{F}_i \psi_i = \sum_j \epsilon_{ij} \ \psi_j \quad (\text{HF equation})$$

- Fock-operator : $\hat{F}_i \equiv \hat{H}^{core} + \sum_{j=1}^{N/2} (2\hat{J}_j \hat{K}_j)$ [for closed-shell systems]
- canonical (diagonal) form : $\hat{F}_i \psi_i = \epsilon_i \psi_i$ (ϵ_i = orbital energy)
- may also use Kohn-Sham (DFT) $\hat{F}^{\rm KS}$ and KS orbitals

HF BO MD :

$$\begin{cases} M_I \ddot{R}_I(t) = -\frac{\partial}{\partial R_I} \langle \Psi_0^{\rm HF} | H_e | \Psi_0^{\rm HF} \rangle & (\Psi_0^{\rm HF} = \det\{\psi_i\}) \\ 0 = -\hat{F}_i \psi_i + \sum_j \epsilon_{ij} \psi_j \end{cases}$$

This set of equations can be derived from an Extended Lagrangian :

$$\mathcal{L}_{\rm BO} = \sum_{I} \frac{1}{2} M_{I} \dot{R}_{I}^{2} - \langle \Psi_{0}^{\rm HF} | H_{e} | \Psi_{0}^{\rm HF} \rangle + \sum_{i,j} \epsilon_{ij} (\langle \psi_{i} | \psi_{j} \rangle - \delta_{ij})$$

by assuming that the <u>Euler-Lagrange equation</u> of the classical mechanics applies for both the nuclear and electronic (orbital) degrees of freedom

$$\Rightarrow \text{Euler-Lagrange eq}: \quad \frac{d}{dt} \frac{\partial \mathcal{L}_{\text{BO}}}{\partial \dot{q}} - \frac{\partial \mathcal{L}_{\text{BO}}}{\partial q} = 0 \quad \text{for} \quad q = R_I, \psi_i, \psi_i^*$$
(Note : functional derivatives for ψ_i and ψ_i^*)

5.2.4 Car-Parrinello MD

Introduce : <u>fictious mass</u> and <u>kinetic energy</u> for electronic (orbital) degrees of freedom \Rightarrow Extended Lagrangian :

$$\mathcal{L}_{\rm CP} = \sum_{I} \frac{1}{2} M_I \dot{R}_I^2 + \sum_{i} \frac{1}{2} \mu_i |\dot{\psi}_i|^2 - \langle \Psi_0^{\rm HF} | H_e | \Psi_0^{\rm HF} \rangle + \text{constraints}$$

e.g., constraints = MO orthonormality = $\sum_{i,j} \epsilon_{ij} (\langle \psi_i | \psi_j \rangle - \delta_{ij})$

$$\text{Euler-Lagrange eq} \Rightarrow \begin{cases} M_I \ddot{R}_I(t) = -\frac{\partial}{\partial R_I} \langle \Psi_0^{\text{HF}} | H_e | \Psi_0^{\text{HF}} \rangle + \frac{\partial}{\partial R_I} \{ \text{constraints} \} \\ \\ \mu_i \ddot{\psi}_i(t) = -\frac{\delta}{\delta \psi_i^*} \langle \Psi_0^{\text{HF}} | H_e | \Psi_0^{\text{HF}} \rangle + \frac{\delta}{\delta \psi_i^*} \{ \text{constraints} \} \end{cases}$$

Car-Parrinello HF MD

$$\begin{pmatrix} M_I \ddot{R}_I(t) &= -\frac{\partial}{\partial R_I} \langle \Psi_0^{\rm HF} | H_e | \Psi_0^{\rm HF} \rangle & (\Psi_0^{\rm HF} = \det\{\psi_i\}) \\ \\ \mu_i \ddot{\psi}_i(t) &= -\hat{F}_i \psi_i + \sum_j \epsilon_{ij} \psi_j \\ \end{pmatrix}$$

(may also use Kohn-Sham Fock operator \hat{F}^{KS})

- Electronic (orbital) degrees of freedom (El-DoF) are treated as dynamical variables
- No (strict) minimization in the MO $\{\psi_i\}$ -space
- Deviate from BO-MD due to thermal fluctuations of the El-DoF
- The dynamics of the El-DoF must be kept cool (eg using constraints)

Diagram : CP-MD trajectory in the coordinate and orbital space

6 Molecular Dynamics Simulation

6.1 Summary of Classical Mechanics

• Newtonian EOM

$$m\ddot{x} = F = -\frac{\partial V(x)}{\partial x}$$

• Principle of Least Action

Action :
$$I \equiv \int_{t_1}^{t_2} \mathcal{L}(x, \dot{x}) dt$$

The classical trajectory $x(t_1) \to x(t_2)$ minimizes the action I against small variation $\delta x(t)$ (with fixed ends $\delta x(t_1) = \delta x(t_2) = 0$).

$$\delta I = \int_{t_1}^{t_2} dt \, \delta \mathcal{L} = \int_{t_1}^{t_2} dt \left(\frac{\partial \mathcal{L}}{\partial x} \delta x + \frac{\partial \mathcal{L}}{\partial \dot{x}} \delta \dot{x} \right)$$
$$= \int_{t_1}^{t_2} dt \left\{ \frac{\partial \mathcal{L}}{\partial x} - \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{x}} \right) \right\} \delta x + \frac{\partial \mathcal{L}}{\partial \dot{x}} \delta x \Big|_{t_1}^{t_2}$$

Stationary condition $\delta I = 0$ for arbitrary $\delta x(t)$

$$\Rightarrow \mathbf{Euler} - \mathbf{Lagrange} \ \mathbf{eq} : \ \frac{\partial \mathcal{L}}{\partial x} - \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{x}} \right) = 0$$

This is easily seen to give the Newtonian EOM for $\mathcal{L} = T - V = \frac{m}{2}\dot{x}^2 - V(x)$

• Hamiltonian EOM : Momentum and Hamiltonian are defined by

$$p \equiv \frac{\partial \mathcal{L}}{\partial \dot{x}}$$
 and $H \equiv p\dot{x} - \mathcal{L}$

For Cartesian coordinates, we get $p = m\dot{x}$ and $H = p^2/2m + V(x)$, and it is easy to see that the following Hamiltonian EOM is equivalent to Newtonian EOM:

$$\dot{x} = \frac{\partial H}{\partial p}$$
 and $\dot{p} = -\frac{\partial H}{\partial x}$

Lagrange and Hamilton theories are more flexible and convenient when dealing with general coordinate systems other than the Cartesian.

6.2 Integration

6.2.1 Verlet algorithm

$$\mathbf{r}(t+\delta t) = \mathbf{r}(t) + \dot{\mathbf{r}}(t)\delta t + \frac{1}{2}\ddot{\mathbf{r}}(t)\delta t^{2} + \cdots$$
$$= \mathbf{r}(t) + \mathbf{v}(t)\delta t + \frac{1}{2}\mathbf{a}(t)\delta t^{2} + \cdots$$
$$\mathbf{r}(t-\delta t) =$$
$$\mathbf{r}(t+\delta t) = 2\mathbf{r}(t) - \mathbf{r}(t-\delta t) + \mathbf{a}(t)\delta t^{2}$$

- error is of order $\mathcal{O}(\delta t^4)$
- time-reversible
- requires storage of the previous position $\mathbf{r}(t + \delta t)$

 \Rightarrow

• small term $\mathbf{a}(t)\delta t^2$ is added to a difference of large terms $2\mathbf{r}(t) - \mathbf{r}(t - \delta t)$

 \Rightarrow numerical round-off imprecisions

• velocities are unnecessary to evolve the trajectory, but needed when calculating the kinetic energy

$$\mathbf{v}(t) = \frac{\mathbf{r}(t+\delta t) - \mathbf{r}(t-\delta t)}{2\delta t}$$

- error is of order $\mathcal{O}(\delta t^3)$
- small difference is divided by the small timestep \Rightarrow numerical imprecisions

6.2.2 Leap-frog algorithm

Propagate position and velocity

$$\mathbf{r}(t+\delta t) = \mathbf{r}(t) + \mathbf{v}(t+\frac{\delta t}{2})\delta t$$
$$\mathbf{v}(t+\frac{\delta t}{2}) = \mathbf{v}(t-\frac{\delta t}{2}) + \mathbf{a}(t)\delta t$$



- mathematically equivalent to Verlet method (easily verified by eliminating the velocities)
- velocities (& kinetic energy) at time t

$$\mathbf{v}(t) = \frac{\mathbf{v}(t + \frac{\delta t}{2}) + \mathbf{v}(t - \frac{\delta t}{2})}{2}$$

- advantages over the original Verlet
 - less problematic on the numerical round-off due to taking differences
 - explicit appearance of velocities
 - criticisms : treatment of velocities still not very satisfactory

6.2.3 Velocity-Verlet algorithm

$$\mathbf{r}(t+\delta t) = \mathbf{r}(t) + \mathbf{v}(t)\delta t + \frac{1}{2}\mathbf{a}(t)\delta t^{2}$$
$$\mathbf{v}(t+\frac{\delta t}{2}) = \mathbf{v}(t) + \mathbf{a}(t)\frac{\delta t}{2}$$
$$\mathbf{v}(t+\delta t) = \mathbf{v}(t+\frac{\delta t}{2}) + \mathbf{a}(t+\delta t)\frac{\delta t}{2}$$

• mathematically equivalent to the previous two

6.3 Treatment of Molecules

• Time scales :

bond stretch < bend < torsion < collective motions < rotation < translation

- Fixing bond lengths (to save CPU)
 - 1. treat as a rigid body (small molecules such as H_2O)
 - 2. transform the EOM to internal coordinates (e.g., GF-matrix method)
 - 3. introduce bond constraint condition to the Lagrangian
 - \Rightarrow constrained EOM (SHAKE and RATTLE methods)
- Multiple time step method(s)
 - small time step for fast motions
 - frequent update of short-range interactions

6.3.1 Multiple time step method (r-RESPA)*

r-RESPA = reversible REference System Propagator Algorithm Classical Liouville operator :

$$iL \equiv \{..., H\} = \sum_{i=1}^{f} \left[\frac{\partial H}{\partial p_i} \frac{\partial}{\partial q_i} - \frac{\partial H}{\partial q_i} \frac{\partial}{\partial p_i} \right]$$

Poisson bracket :
$$\{A, B\} = \sum_{i=1}^{f} \left[\frac{\partial A}{\partial q_i} \frac{\partial B}{\partial p_i} - \frac{\partial A}{\partial p_i} \frac{\partial B}{\partial q_i} \right]$$

Propagation of the phase-space point $\Gamma = \{q_i(t), p_i(t)\}\$

$$\Gamma(t + \Delta t) = e^{iL\Delta t} \ \Gamma(t)$$

In Cartesian coordinate with $H = \sum_{i} \frac{p_i^2}{2m_i} + V(\mathbf{x}), \quad p_i = m_i v_i, \quad \left(F_i = -\frac{\partial V}{\partial x_i} = \text{force}\right)$

$$iL = \sum_{i} \left[v_i \frac{\partial}{\partial x_i} + \frac{F_i}{m_i} \frac{\partial}{\partial v_i} \right]$$

Using $e^{c\frac{\partial}{\partial y}}f(y) = f(y+c)$, we find :

- $e^{v\Delta t \frac{\partial}{\partial x}}$ propagates x to $x + v\Delta t$
- $e^{\Delta t \frac{F}{m} \frac{\partial}{\partial v}}$ propagates v to $v + \frac{F}{m} \Delta t$

Trotter decomposition

$$e^{i(L_1+L_2)\Delta t} = e^{iL_1\Delta t/2}e^{iL_2\Delta t}e^{iL_1\Delta t/2} + \mathcal{O}(\Delta t^3)$$

If we choose : $iL_1 = \frac{F}{m} \frac{\partial}{\partial v}, \quad iL_2 = v \frac{\partial}{\partial x}$

$$\Gamma(t + \Delta t) = e^{\frac{\Delta t}{2} \frac{F}{m} \frac{\partial}{\partial v}} e^{\Delta t v \frac{\partial}{\partial x}} e^{\frac{\Delta t}{2} \frac{F}{m} \frac{\partial}{\partial v}} \cdot \Gamma(t) + \mathcal{O}(\Delta t^3)$$

From right to left :

- $e^{\frac{\Delta t}{2}\frac{F}{m}\frac{\partial}{\partial v}}$ propagates v to $v + \frac{F}{m}\frac{\Delta t}{2}$
- $e^{\Delta t v \frac{\partial}{\partial x}}$ propagates x to $x + v \Delta t$
- $e^{\frac{\Delta t}{2}\frac{F}{m}\frac{\partial}{\partial v}}$ propagates v to $v + \frac{F}{m}\frac{\Delta t}{2}$ (with updated force F(x))

This is exactly the Velocity-Verlet algorithm

Decomposition of forces : (fast/slow, tight/soft, short/long-range etc.)

$$F = F_{\text{fast}} + F_{\text{slow}}$$

Accordingly, $iL_1 = \frac{F_{\text{slow}}}{m} \frac{\partial}{\partial v} \quad iL_2 = v \frac{\partial}{\partial x} + \frac{F_{\text{fast}}}{m} \frac{\partial}{\partial v}$, Then, the propagator will be

$$e^{\frac{\Delta t}{2}\frac{F_{\mathrm{slow}}}{m}\frac{\partial}{\partial v}}e^{\Delta t\left(v\frac{\partial}{\partial x}+\frac{F_{\mathrm{fast}}}{m}\frac{\partial}{\partial v}\right)}e^{\frac{\Delta t}{2}\frac{F_{\mathrm{slow}}}{m}\frac{\partial}{\partial v}}$$

We further decompose the propagator in the middle into n micro-steps with $\delta t \equiv \Delta t/n$

$$e^{\frac{\Delta t}{2}\frac{F_{\mathrm{slow}}}{m}\frac{\partial}{\partial v}} \left[e^{\frac{\delta t}{2}\frac{F_{\mathrm{fast}}}{m}\frac{\partial}{\partial v}} e^{\delta t v \frac{\partial}{\partial x}} e^{\frac{\delta t}{2}\frac{F_{\mathrm{fast}}}{m}\frac{\partial}{\partial v}} \right]^n e^{\frac{\Delta t}{2}\frac{F_{\mathrm{slow}}}{m}\frac{\partial}{\partial v}}$$

Implementation It might be easier to see the code :

$$\begin{array}{ll} \delta t = \Delta t/n & ! \text{ micro-timestep (for fast motions)} \\ \text{do istep } = 1, \text{ nstep} & ! \text{ overall simulation steps} \\ \mathbf{v} = \mathbf{v} + (\Delta t/2) \cdot (\mathbf{F}_{\text{slow}}/m) \\ \text{do j} = 1, n & ! \text{ inner loop for fast motions} \\ \mathbf{v} = \mathbf{v} + (\delta t/2) \cdot (\mathbf{F}_{\text{fast}}/m) \\ \mathbf{x} = \mathbf{x} + \delta t \cdot \mathbf{v} \\ \text{ call calculate_force}(\mathbf{F}_{\text{fast}}) \\ \mathbf{v} = \mathbf{v} + (\delta t/2) \cdot (\mathbf{F}_{\text{fast}}/m) \\ \text{end do} \\ \text{call calculate_force}(\mathbf{F}_{\text{slow}}) \\ \mathbf{v} = \mathbf{v} + (\Delta t/2) \cdot (\mathbf{F}_{\text{slow}}/m) \\ \text{end do} \\ \text{call calculate_force}(\mathbf{F}_{\text{slow}}) \\ \mathbf{v} = \mathbf{v} + (\Delta t/2) \cdot (\mathbf{F}_{\text{slow}}/m) \\ \text{end do} \\ \text{call calculate_force}(\mathbf{F}_{\text{slow}}) \\ \mathbf{v} = \mathbf{v} + (\Delta t/2) \cdot (\mathbf{F}_{\text{slow}}/m) \\ \text{end do} \\ \end{array}$$

6.4 Constant Temperature and Pressure Methods

6.4.1 Common Statistical Ensembles

- constant NVE (microcanonical)
- constant NVT (canonical)
- constant NPT (isothermal-isobaric)
- constant μ VT (grand canonical) [μ = chemical potential]

Straightforward / standard use of :

- MD \Rightarrow microcanonical (energy conservation of classical mech.)
- $MC \Rightarrow canonical$ (Metropolis algorithm)

Statistical average (constant temperature)

$$\langle A(q,p)\rangle = \frac{1}{Q} \int \int dp \, dq \, A(q,p) \, e^{-H(q,p)/k_B T}$$

where Q is the partition function : $Q \equiv \int \int dp \ dq \ e^{-H(q,p)/k_B T}$

6.4.2 Temperature and Pressure from MD

Equipartition theorem :

$$\langle \frac{p_{\alpha i}^2}{2m_i} \rangle = \frac{k_B T}{2} \quad (\alpha = x, y, z)$$

i.e. average kinetic energy of $k_B T/2$ for each degree of freedom

The kinetic temperature is thus computed in the classical MD by

$$T = \frac{1}{3Nk_B} \langle \sum_i \frac{\mathbf{p}_i^2}{m_i} \rangle$$

Pressure from MD :

Virial:
$$W \equiv \frac{1}{3} \sum_{i=1}^{N} \mathbf{r}_i \cdot \mathbf{f}_i^{\text{int}} \qquad \left(\mathbf{f}_i^{\text{int}} = -\frac{\partial V}{\partial \mathbf{r}_i}\right)$$

 $PV = Nk_BT + \langle W \rangle$

6.4.3 Constant NVT MD*

Extended system method (Nosé-Hoover)

Couple with <u>external heat bath</u> \Rightarrow **friction** parameter η (fictious mass Q)

$$\dot{\mathbf{r}}_{i} = \frac{\mathbf{p}_{i}}{m_{i}}, \quad \dot{\mathbf{p}}_{i} = \mathbf{f}_{i} - \frac{p_{\eta}}{Q}\mathbf{p}_{i}$$
$$\dot{\eta} = \frac{p_{\eta}}{Q}, \quad \dot{p}_{\eta} = \sum_{i=1}^{N} \frac{\mathbf{p}_{i}^{2}}{m_{i}} - N_{f}k_{B}T$$

 $(N_f = \text{number of (unconstrained) degrees of freedom} = 3N - N_c)$

- proven to generate <u>canonical ensemble</u>
- Conserved quantity (for coding checks) :

$$E = \sum_{i} \frac{\mathbf{p}_i^2}{2m_i} + V(\mathbf{r}) + \frac{p_\eta^2}{2Q} + N_f k_B T \eta$$

6.4.4 Constant Pressure MD*

Constant pressure P in simulation $\Leftarrow Volume \text{ control}$ (as a dynamical variable)

 \Rightarrow coordinate scaling : $\mathbf{r}_i = V^{1/3} \mathbf{s}_i$

extended Lagrangian : $(Q = \underline{\text{fictious}} \text{ mass for } V)$ $\mathcal{L} = \frac{1}{2} \sum_{i} m_i \mathbf{v}_i^2 - V(\mathbf{r}) + \frac{1}{2} Q \dot{V}^2 - PV$ Fuler Lagrange eq.: $d \partial \mathcal{L} = \partial \mathcal{L} = 0$ for q = q. V

Euler-Lagrange eq :

$$\frac{a}{dt}\frac{\partial L}{\partial \dot{q}} - \frac{\partial L}{\partial q} = 0 \quad \text{for } q = \mathbf{s}_i, V$$
$$\Rightarrow \ddot{\mathbf{s}}_i = \frac{1}{V^{1/3}}\frac{\mathbf{f}_i}{m_i} - \frac{2}{3V}\dot{\mathbf{s}}\dot{V}, \qquad \ddot{V} = \frac{1}{Q}(\mathcal{P} - P)$$
$$\mathcal{P} \equiv \frac{1}{3V}(\sum_i m_i \mathbf{v}_i^2 + W) \qquad (W = \text{virial})$$

7 Data Analysis

7.1 Static Properties

Ergodic hypothesis : Statistical ensemble average = average over long time

$$\langle A \rangle = \frac{1}{\tau_{\text{run}}} \int_0^{\tau_{\text{run}}} A(t) \ dt = \frac{1}{N_{\text{run}}} \sum_{k=1}^{N_{\text{run}}} A_k$$

where $\tau_{\rm run} = N_{\rm run} \Delta t$ ($N_{\rm run}$ steps, $A_k = A(k\Delta t)$)

• RMS deviation = $\sqrt{\langle \delta A^2 \rangle}$ $(\delta A \equiv A - \langle A \rangle)$



Practical



Method 2: "on-the-fly" summing up.

For RMS, we sum up $\delta A = A - \langle A \rangle$. However, we don't know $\langle A \rangle$ until the end of simulation. The following conversion is then useful:

$$\langle \delta A^2 \rangle = \langle (A - \langle A \rangle)^2 \rangle = \dots = \langle A^2 \rangle - \langle A \rangle^2$$

```
sum = 0 ; sum2 = 0
do istep = 1, nstep ! overall simulation steps
...
call calculate_quantities(A)
sum = sum + A
sum2 = sum2 + A<sup>2</sup>
...
end do
average = sum/nstep
variance = sum2/nstep - average<sup>2</sup>
RMS = \sqrt{variance}
```

7.2 Radial disribution function

Example : Ion pair in water



7.3 Time correlation function



correlation between points with time interval τ

$$C_{AA}(\tau) = \langle \delta A(0)\delta A(\tau) \rangle = \frac{1}{t_{\rm run} - \tau} \int_0^{t_{\rm run} - \tau} \delta A(t) \, \delta A(t+\tau) \, dt$$

- $C_{AA}(0) = 1$
- For random motions (e.g. in liquids)

 $C_{AA}(t) \to 0 \text{ as } t \to +\infty$ (loss of correlation)

• For "regular" motions (eg. harmonic oscillators / phonons in "perfect" solids)

$$\langle x(0)x(t)\rangle = x(0)^2 \cos \omega t$$

• For (slightly) disordered set of oscillators \Rightarrow "dephasing"







7.3.1 Relaxation Phenomena

Onsager's Regression Hypothesis



Microscopically proven by Fluctuation-dissipation theorem in the Linear-Response limit

7.3.2 Various Applications

- Transport properties (Diffusion constant) \Leftarrow velocity TCF
- Microwave & IR spectra \Leftarrow dipole TCF
- Electronic spectra \Leftarrow transition dipole TCF
- Electron / excitation transfer rates \leftarrow TCF of energy gap (Fermi Golden Rule)
- Chemical reaction rates $\Leftarrow \underline{\text{flux-flux}}$ TCF

cf. G C Schatz & M A Ratner, "Quantum Mechanics in Chemistry" (Prentice Hall, 1993)

Diffusion constant \equiv mean-squares displacement (Einstein relation)

 $\langle |\mathbf{r}(t) - \mathbf{r}(0)|^2 \rangle = 6Dt$

Relation to velocity TCF :

$$\mathbf{r}(t) - \mathbf{r}(0) = \int_0^t \mathbf{v}(\tau) d\tau \quad \Rightarrow \quad 6Dt = \int_0^t d\tau_1 \int_0^t d\tau_2 \langle \mathbf{v}(\tau_1) \mathbf{v}(\tau_2) \rangle$$

 $\frac{\partial}{\partial t}$ both sides

$$6D = 2\int_0^t d\tau \langle \mathbf{v}(\tau)\mathbf{v}(t) \rangle = 2\int_0^t d\tau \langle \mathbf{v}(0)\mathbf{v}(t-\tau) \rangle$$

 $\leftarrow \text{ TCF depends only on time interval (in stationary equilibrium)}$ Changing the integration variable from τ to $\tau' \equiv t - \tau$,

$$D = \frac{1}{3} \int_0^t d\tau' \langle \mathbf{v}(0) \mathbf{v}(\tau') \rangle$$

8 Monte Carlo Simulation

Monte Carlo integration \Leftarrow random sampling

$$I = \int_0^1 f(x) dx \simeq \frac{1}{N_{\text{sample}}} \sum_{i=1}^{N_{\text{sample}}} f(x_i)$$

$$\{x_i\}$$
 = uniform random numbers in [0, 1]

Statistical average (constant temperature) \Leftarrow **Phase-space integration**

$$\langle A(q,p)\rangle = \frac{1}{Q} \int \int dp \, dq \, A(q,p) \, e^{-H(q,p)/k_B T}$$

where Q is the partition function : $Q \equiv \int \int dp \; dq \; e^{-H(q,p)/k_BT}$

For momentum-independent quantities A(q) (with $H = \sum_i \mathbf{p}_i^2 / 2m_i + V(q)$)

\Rightarrow Configuration space integration

$$\langle A \rangle = \frac{1}{Z} \int dq A(q) e^{-V(q)/k_B T}$$

where $Z = \int dq e^{-V(q)/k_B T}$

8.1 Standard MC (Metropolis algorithm)

Metropolis MC

- generates configurations R in canonical ensemble
- Core algorithm :

• Statistical average is calculated by:

$$\langle A \rangle = \frac{1}{N_{\text{step}}} \sum_{i=1}^{N_{\text{step}}} A(\mathbf{R}_i)$$

MC vs MD

- direct generation of canonical ensemble (straightforward MD \Rightarrow microcanonical)
- Phase-space / configration-space average (MD analysis ⇒ time average assuming the ergodic hypothesis)
- no need to evaluate forces
- no time evolution

8.2 Umbrella Sampling Technique

Finite length of MC sampling

 \Rightarrow the system may be trapped in local potential minima.

In order to extend the sampling to high potential (unstable) configurations, we augment a bias (weight / window / umbrella) potential W(q) to the original (unbiased) potential V(q). The statistical average obtained from this biased simulation is

$$\langle A(q) \rangle_w = \frac{1}{Q_w} \int dq \ A(q) \ e^{-\beta(V(q) + W(q))} \qquad \left(Q_w = \int dq \ e^{-\beta(U(q) + W(q))} \right)$$

The statistics of the original (unbiased) system are reproduced by

$$\begin{split} \langle A(q) \rangle_0 &= \frac{1}{Q_0} \int dq \; A(q) \; e^{-\beta V(q)} \times \frac{Q_w}{Q_w} \\ &= \frac{Q_w}{Q_0} \frac{1}{Q_w} \; \int dq \; A(q) \; e^{+\beta W(q)} e^{-\beta (V(q)+W(q))} = \frac{Q_w}{Q_0} \; \langle A(q) \; e^{+\beta W(q)} \rangle_u \\ &= \frac{\langle A(q) \; e^{+\beta W(q)} \rangle_w}{\langle e^{+\beta W(q)} \rangle_w} = \langle e^{-\beta W(q)} \rangle_0 \; \langle A e^{+\beta W(q)} \rangle_w \end{split}$$

9 Free Energy Surfaces

Remember that the Gibbs free energy is related to the equilibrium constant and thus the probability distributions of the reactant and product species. For example, for $A \rightleftharpoons B$,

$$e^{-\Delta G/k_BT} = K = \frac{[B]}{[A]} = \frac{\text{Prob. B}}{\text{Prob. A}}$$

This would suggest the following generalization to more general "states" of the system

$$\Delta G \equiv G_2 - G_1 = -k_B T \ln \left(\frac{\text{Prob. State 2}}{\text{Prob. State 1}}\right)$$

Now, let X be some coordinate(s) of the system. This may be a position coordinate itself or a function of positions. The free energy curves or surfaces along X can be defined and calculated from the probability distribution of P(X)

$$G(X) = -k_B T \ln P(X)$$
 or $G(X_2) - G(X_1) = -k_B T \ln \left(\frac{P(X_2)}{P(X_1)}\right)$

For example, when P(X) is a Gaussian distribution

$$P(X) \propto e^{-aX^2}$$

then the free energy curve G(X) is a harmonic potential

$$G(X) = -k_B T \ln e^{-aX^2} + C = k_B T a X^2 + C$$

where C is just a constant coming from the normalization factor of P(X). It is very straightforward to calculated P(X) from simulations. The umbrella sampling method discussed in the previous section can be employed for high energy (less probable) regions along X.